

## Section 17. Electrical Specifications

### 17.1 Absolute Maximum Ratings

Table 17-1 lists the absolute maximum ratings.

**Table 17-1. Absolute Maximum Ratings**

Item	Symbol	Rating	Unit
Supply voltage	V <sub>CC</sub>	-0.3 to +7.0	V
Programming voltage	V <sub>PP</sub>	-0.3 to +13.5	V
Input voltage			
Ports 1 – 6, 8, 9	V <sub>in</sub>	-0.3 to V <sub>CC</sub> + 0.3	V
Port 7	V <sub>in</sub>	-0.3 to AV <sub>CC</sub> + 0.3	V
Analog supply voltage	AV <sub>CC</sub>	-0.3 to +7.0	V
Analog input voltage	V <sub>AN</sub>	-0.3 to AV <sub>CC</sub> + 0.3	V
Operating temperature	T <sub>opr</sub>	Regular specifications: -20 to +75	°C
		Wide-range specifications: -40 to +85	°C
Storage temperature	T <sub>stg</sub>	-55 to +125	°C

**Note:** The input pins have protection circuits that guard against high static voltages and electric fields, but these high input-impedance circuits should never receive overvoltages exceeding the absolute maximum ratings shown in table 17-1.

### 17.2 Electrical Characteristics

#### 17.2.1 DC Characteristics

Table 17-2 lists the DC characteristics of the H8/330.

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**Table 17-2. DC Characteristics**Conditions:  $V_{CC} = 5.0V \pm 10\%$ \*,  $AV_{CC} = 5.0V \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0V$ , $T_a = -20$  to  $75^\circ C$  (regular specifications),  $T_a = -40$  to  $85^\circ C$  (wide-range specifications)

Item		Symbol	Measurement			Unit	conditions
			min	typ	max		
Schmitt trigger input voltage (1)	P67 – P62, P60,	$V_{T^-}$	1.0	–	–	V	
	P86 – P80,	$V_{T^+}$	–	–	3.5	V	
	P97, P94 – P90	$V_{T^+} - V_{T^-}$	0.4	–	–	V	
Input High voltage (2)	RES, STBY, MD1, MD0	$V_{IH}$	$V_{CC} - 0.7$	–	$V_{CC} + 0.3$	V	
	EXTAL, NMI		$V_{CC} \times 0.7$	–	$V_{CC} + 0.3$	V	
	P77 – P70		2.2	–	$AV_{CC} + 0.3$	V	
Input High voltage (3)	Input pins other than (1) and (2)	$V_{IH}$	2.2	–	$V_{CC} + 0.3$	V	
Input Low voltage (3)	RES, STBY	$V_{IL}$	-0.3	–	0.5	V	
	MD1, MD0						
Input Low voltage	Input pins other than (1) and (3)	$V_{IL}$	-0.3	–	0.8	V	
Output High voltage	All output pins	$V_{OH}$	$V_{CC} - 0.5$	–	–	V	$I_{OH} = -200\mu A$
			3.5	–	–	V	$I_{OH} = -1.0mA$
Output Low voltage	All output pins Ports 1 and 2	$V_{OL}$	–	–	0.4	V	$I_{OL} = 1.6mA$
			–	–	1.0	V	$I_{OL} = 10.0mA$
Input leakage current	RES	$I_{inl}$	–	–	10.0	$\mu A$	$V_{in} = 0.5V$ to $V_{CC} - 0.5V$
	STBY, NMI, MD1, MD0		–	–	1.0	$\mu A$	$V_{in} = 0.5V$ to $AV_{CC} - 0.5V$
	P77 – P70		–	–	1.0	$\mu A$	$V_{in} = 0.5V$ to $AV_{CC} - 0.5V$
Leakage current in 3-state (off state)	Ports 1, 2, 3 4, 5, 6, 8, 9	$I_{TSII}$	–	–	1.0	$\mu A$	$V_{in} = 0.5V$ to $V_{CC} - 0.5V$
Input pull-up MOS current	Ports 1, 2, 3 4, 5, 6, 8, 9	$-I_p$	30	–	250	$\mu A$	$V_{in} = 0V$

\* Connect  $AV_{CC}$  to the power supply (+5V) even when the A/D converter is not used.**HITACHI**

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**Table 17-2. DC Characteristics (cont.)**

Conditions:  $V_{CC} = AV_{CC} = 5.0V \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_a = -20$  to  $75^\circ C$  (regular specifications)  
 $T_a = -40$  to  $85^\circ C$  (wide-range specifications)

Item		Symbol	Measurement			Unit	conditions
			min	typ	max		
Input capacitance	RES (V <sub>PP</sub> )	C <sub>in</sub>	–	–	60	pF	V <sub>in</sub> = 0V
	NMI		–	–	30	pF	
	All input pins except RES and NMI		–	–	15	pF	f = 1MHz T <sub>a</sub> = 25°C
Current dissipation* <sup>1</sup>	Normal operation	I <sub>CC</sub>	–	12	25	mA	f = 6MHz
			–	16	30	mA	f = 8MHz
			–	20	40	mA	f = 10MHz
	Sleep mode		–	8	15	mA	f = 6MHz
			–	10	20	mA	f = 8MHz
			–	12	25	mA	f = 10MHz
Standby modes* <sup>2</sup>		–	0.01	5.0	μA		
Analog supply current	During A/D conversion	A <sub>I<sub>CC</sub></sub>	–	0.6	1.5	mA	
	Waiting		–	0.01	5.0	μA	
RAM standby voltage		V <sub>RAM</sub>	2.0	–	–	V	

\*1 Current dissipation values assume that V<sub>IH min.</sub> = V<sub>CC</sub> – 0.5V, V<sub>IL max.</sub> = 0.5V, all output pins are in the no-load state, and all MOS input pull-ups are off.

\*2 For these values it is assumed that V<sub>RAM</sub> ≤ V<sub>CC</sub> < 4.5V and V<sub>IH min.</sub> = V<sub>CC</sub> × 0.9, V<sub>IL max.</sub> = 0.3V.

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**Table 17-2. DC Characteristics (3V Version) (preliminary)**Conditions:  $V_{CC} = 3.0V \pm 10\%$ ,  $AV_{CC} = 5.0V \pm 10\%^{*1}$ ,  $V_{SS} = AV_{SS} = 0V$ , $T_a = 0$  to  $70^{\circ}C$ 

Item	Symbol	min	typ	max	Measurement		
					Unit	conditions	
Schmitt trigger input voltage* <sup>2</sup>	P67 – P62, P60, P86 – P80, P97, P94 – P90	$V_{T^{-}}$ $V_{T^{+}}$ $V_{T^{+}} - V_{T^{-}}$	$V_{CC} \times 0.15$	–	–	V	V
(1)							
Input High voltage* <sup>2</sup>	RES, STBY, MD1, MD0, EXTAL, NMI, P77 – P70	$V_{IH}$	$V_{CC} \times 0.9$	–	$V_{CC} + 0.3$	V	V
(2)							
	Input pins other than (1) and (2) above		2.0	–	$AV_{CC} + 0.3$	V	V
			2.0	–	$V_{CC} + 0.3$	V	V
Input Low voltage* <sup>2</sup>	RES, STBY, MD1, MD0	$V_{IL}$	–0.3	–	$V_{CC} \times 0.1$	V	V
(3)							
	Input pins other than (1) and (3) above		–0.3	–	0.6	V	V
Output High voltage	All output pins	$V_{OH}$	2.4	–	–	V	$I_{OH} = -500\mu A$
			$V_{CC} - 0.2$	–	–	V	$I_{OH} = -20\mu A$
Output Low voltage	All output pins, Ports 1 and 2	$V_{OL}$	–	–	0.4	V	$I_{OL} = 1.2mA$
			–	–	0.4	V	$I_{OL} = 2.0mA$
Input leakage current	RES, STBY, NMI, MD1, MD0, P77 – P70	$ I_{in} $	–	–	10.0	$\mu A$	$V_{in} = 0.5$ to $V_{CC} - 0.5V$
			–	–	1.0	$\mu A$	$V_{in} = 0.5$ to $AV_{CC} - 0.5V$
Leakage current in 3-state (off state)	Ports 1, 2, 3, 4, 5, 6, 8, 9	$ I_{rs} $	–	–	1.0	$\mu A$	$V_{in} = 0.5$ to $V_{CC} - 0.5V$
Input pull-up MOS current	Ports 1, 2, 3	$-I_p$	3	–	120	$\mu A$	$V_{in} = 5.0V$

**Notes:** \*1 Connect  $AV_{CC}$  to the power supply (+3V) even when the A/D converter is not used.\*2 In the range  $3.3V < V_{CC} < 4.5V$ , for the input levels of  $V_{IH}$  and  $V_{T^{+}}$ , apply the higher of the values given for the 5V and 3V versions. For  $V_{IL}$  and  $V_{T^{-}}$ , apply the lower of the values given for the 5V and 3V versions.**HITACHI**

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**Table 17-2. DC Characteristics (3V Version) (preliminary) (cont.)**Conditions:  $V_{CC} = 3.0V \pm 10\%$ ,  $AV_{CC} = 5.0V \pm 10\%^{*1}$ ,  $V_{SS} = AV_{SS} = 0V$ , $T_a = 0$  to  $70^{\circ}C$ 

Item	Symbol	min	Measurement				
			typ	max	Unit conditions		
Input capacitance	RES	$C_{in}$	—	—	60 pF	$V_{in} = 0V$	
	NMI		—	—	30 pF	$f = 1MHz$	
	All input pins except RES and NMI		—	—	15 pF	$T_a = 25^{\circ}C$	
Current dissipation*1	Normal operation	$I_{CC}$	—	6	—	mA	$f = 3MHz$
	Sleep mode		—	10	15	mA	$f = 5MHz$ , $V_{CC} = 3.3 V$
			—	4	—	mA	$f = 3MHz$
	Standby modes*2		—	6	10	mA	$f = 5MHz$ , $V_{CC} = 3.3 V$
Analog supply current	during A/D or D/A conversion	$A_{ICC}$	—	—	1.5	mA	
	Waiting		—	0.01	5.0	$\mu A$	
RAM backup voltage (in standby modes)	$V_{RAM}$	2.0	—	—	—	V	

**Notes:** \*1 Current dissipation values assume that  $V_{IH\ min} = V_{CC} - 0.5V$ ,  $V_{IL\ max} = 0.5V$ , all output pins are in the no-load state, and all input pull-up transistors are off.

\*2 For these values it is assumed that  $V_{RAM} \leq V_{CC} < 2.7V$  and  $V_{IH\ min} = V_{CC} \times 0.9$ ,  $V_{IL\ max} = 0.3V$ .

**Table 17-3. Allowable Output Current Sink Values**Conditions:  $V_{CC} = AV_{CC} = 5.0V \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0V$ , $T_a = -20$  to  $75^{\circ}C$  (regular specifications) $T_a = -40$  to  $85^{\circ}C$  (wide-range specifications)

Item	Symbol	min	typ	max	Unit
Allowable output Low current sink (per pin)	Ports 1 and 2	$I_{OL}$	—	—	10 mA
	Other output pins		—	—	2.0 mA
Allowable output Low current sink (total)	Ports 1 and 2, total	$\Sigma I_{OL}$	—	—	80 mA
	All output pins		—	—	120 mA
Allowable output High current sink (per pin)	All output pins	$-I_{OH}$	—	—	2.0 mA
Allowable output High current sink (total)	Total of all output	$\Sigma -I_{OH}$	—	—	40 mA

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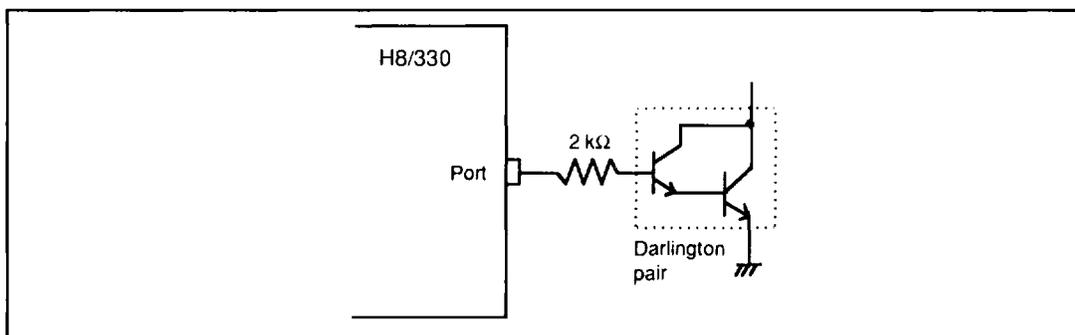
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**Table 17-3. Allowable Output Current Sink Values (3V Version) (Preliminary)**

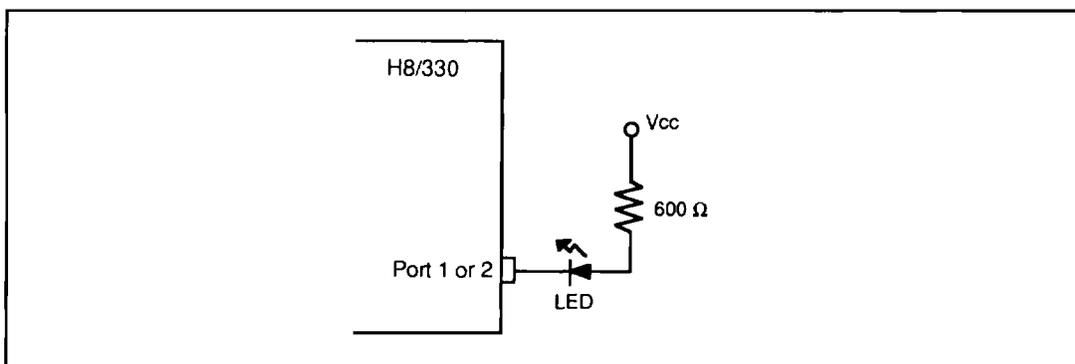
Conditions:  $V_{CC} = 3.0V \pm 10\%$ ,  $AV_{CC} = 5.0V \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_a = -0$  to  $75^\circ C$

Item	Symbol	min	typ	max	Unit	
Allowable output Low current sink (per pin)	Ports 1 and 2	$I_{OL}$	—	—	10	mA
	Other output pins		—	—	2.0	mA
Allowable output Low current sink (total)	Ports 1 and 2, total	$\Sigma I_{OL}$	—	—	80	mA
	Total of all output		—	—	120	mA
Allowable output High current sink (per pin)	All output pins	$-I_{OH}$	—	—	2	mA
Allowable output High current sink (total)	Total of all output	$\Sigma -I_{OH}$	—	—	40	mA

**Note:** To avoid degrading the reliability of the chip, be careful not to exceed the output current sink values in table 17-3. In particular, when driving a Darlington transistor pair or LED directly, be sure to insert a current-limiting resistor in the output path. See figures 17-1 and 17-2.



**Figure 17-1. Example of Circuit for Driving a Darlington Pair**



**Figure 17-2. Example of Circuit for Driving a LED**

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## 17.2.2 AC Characteristics

The AC characteristics of the H8/330 chip are listed in three tables. Bus timing parameters are given in table 17-4, control signal timing parameters in table 17-5, and timing parameters of the on-chip supporting modules in table 17-6.

**Table 17-4. Bus Timing**

Condition A:  $V_{CC} = 5.0V \pm 10\%$ ,  $\emptyset = 0.5$  to 10MHz,  $V_{SS} = 0V$ ,

$T_a = -20$  to  $75^\circ C$  (regular specifications),

$T_a = -40$  to  $85^\circ C$  (wide-range specifications)

Condition B:  $V_{CC} = 3.0V \pm 10\%$ ,  $V_{SS} = 0V$ ,  $\emptyset = 0.5$ MHz to maximum operating frequency,

$T_a = 0$  to  $75^\circ C$

Measurement Item	Symbol	Measurement conditions	Condition B		Condition A				Unit		
			5MHz	6MHz	8MHz	10MHz					
Clock cycle time	t <sub>cy</sub>	Fig. 17-4	200	2000	166.7	2000	125	2000	100	2000	ns
Clock pulse width Low	t <sub>CL</sub>	Fig. 17-4	70	—	65	—	45	—	35	—	ns
Clock pulse width High	t <sub>CH</sub>	Fig. 17-4	70	—	65	—	45	—	35	—	ns
Clock rise time	t <sub>Cr</sub>	Fig. 17-4	—	30	—	15	—	15	—	15	ns
Clock fall time	t <sub>Cf</sub>	Fig. 17-4	—	30	—	15	—	15	—	15	ns
Address delay time	t <sub>AD</sub>	Fig. 17-4	—	100	—	70	—	60	—	55	ns
Address hold time	t <sub>AH</sub>	Fig. 17-4	30	—	30	—	25	—	20	—	ns
Address strobe delay time	t <sub>ASD</sub>	Fig. 17-4	—	90	—	70	—	60	—	50	ns
Write strobe delay time	t <sub>WSD</sub>	Fig. 17-4	—	120	—	70	—	60	—	50	ns
Strobe delay time	t <sub>SD</sub>	Fig. 17-4	—	90	—	70	—	60	—	50	ns
Write strobe pulse width	t <sub>WSW</sub>	Fig. 17-4	200	—	200	—	150	—	120	—	ns
Address setup time 1	t <sub>AS1</sub>	Fig. 17-4	25	—	25	—	20	—	15	—	ns
Address setup time 2	t <sub>AS2</sub>	Fig. 17-4	105	—	105	—	80	—	65	—	ns
Read data setup time	t <sub>RDS</sub>	Fig. 17-4	80	—	70	—	55	—	50	—	ns
Read data hold time	t <sub>RDH</sub>	Fig. 17-4	10	—	0	—	0	—	0	—	ns
Write data delay time	t <sub>WDD</sub>	Fig. 17-4	—	140	—	70	—	60	—	60	ns
Read data access time	t <sub>ACC</sub>	Fig. 17-4	—	300	—	270	—	190	—	160	ns
Write data setup time	t <sub>WDS</sub>	Fig. 17-4	10	—	30	—	15	—	10	—	ns
Write data hold time	t <sub>WDH</sub>	Fig. 17-4	30	—	30	—	25	—	20	—	ns
Wait setup time	t <sub>WTS</sub>	Fig. 17-5	70	—	40	—	40	—	40	—	ns
Wait hold time	t <sub>WTH</sub>	Fig. 17-5	30	—	10	—	10	—	10	—	ns
E clock delay time	t <sub>ED</sub>	Fig. 17-6	—	20	—	20	—	20	—	20	ns
E clock rise time	t <sub>Er</sub>	Fig. 17-6	—	15	—	15	—	15	—	15	ns
E clock fall time	t <sub>Ef</sub>	Fig. 17-6	—	15	—	15	—	15	—	15	ns
Read data hold time (for E clock)	t <sub>RDHE</sub>	Fig. 17-6	0	—	0	—	0	—	0	—	ns
Write data hold time (for E clock)	t <sub>WDHE</sub>	Fig. 17-6	60	—	50	—	40	—	30	—	ns

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**Table 17-5. Control Signal Timing**

Condition A:  $V_{CC} = 5.0V \pm 10\%$ ,  $\emptyset = 0.5$  to 10MHz,  $V_{SS} = 0V$ ,

$T_a = -20$  to  $75^\circ C$  (regular specifications),

$T_a = -40$  to  $85^\circ C$  (wide-range specifications)

Condition B:  $V_{CC} = 3.0V \pm 10\%$ ,  $V_{SS} = 0V$ ,  $\emptyset = 0.5$ MHz to maximum operating frequency,

$T_a = 0$  to  $75^\circ C$

Measurement Item	Symbol	Measurement conditions	Condition B		Condition A				Unit		
			5MHz	6MHz	8MHz	10MHz					
RES setup time	tRESS	Fig. 17-7	300	—	200	—	200	—	200	—	ns
RES pulse width	tRESW	Fig. 17-7	10	—	10	—	10	—	10	—	t <sub>cy</sub>
Mode programming setup time	tMDS	Fig. 17-7	—	—	4	—	4	—	4	—	t <sub>cy</sub>
NMI setup time ( $\overline{NMI}$ , $\overline{IRQ_0}$ to $\overline{IRQ_7}$ )	tNMIS	Fig. 17-8	300	—	110	—	110	—	110	—	ns
NMI hold time ( $\overline{NMI}$ , $\overline{IRQ_0}$ to $\overline{IRQ_7}$ )	tNMIH	Fig. 17-8	10	—	10	—	10	—	10	—	ns
Interrupt pulse width for recovery from soft- ware standby mode ( $\overline{NMI}$ , $\overline{IRQ_0}$ to $\overline{IRQ_2}$ )	tNMIW	Fig. 17-8	300	—	200	—	200	—	200	—	ns
Crystal oscillator settling time (reset)	tOSC1	Fig. 17-9	20	—	20	—	20	—	20	—	ms
Crystal oscillator settling time (software standby)	tOSC2	Fig. 17-10	10	—	10	—	10	—	10	—	ms

**Table 17-6. Timing Conditions of On-Chip Supporting Modules**

Condition A:  $V_{CC} = 5.0V \pm 10\%$ ,  $\emptyset = 0.5$  to 10MHz,  $V_{SS} = 0V$ ,

$T_a = -20$  to  $75^\circ C$  (regular specifications),

$T_a = -40$  to  $85^\circ C$  (wide-range specifications)

Condition B:  $V_{CC} = 3.0V \pm 10\%$ ,  $V_{SS} = 0V$ ,  $\emptyset = 0.5$ MHz to maximum operating frequency,

$T_a = -20$  to  $75^\circ C$

Item	Symbol	Measurement conditions	Condition B		Condition A				Unit		
			5MHz	6MHz	8MHz	10MHz					
FRT Timer output delay time	tFTOD	Fig. 17-11	—	200	—	100	—	100	—	100	ns
Timer input setup time	tFTIS	Fig. 17-11	100	—	50	—	50	—	50	—	ns
Timer clock input setup time	tFTCS	Fig. 17-12	100	—	50	—	50	—	50	—	ns
Timer clock pulse width	tFTCWH	Fig. 17-12	1.5	—	1.5	—	1.5	—	1.5	—	t <sub>cy</sub>

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**Table 17-6. Timing Conditions of On-Chip Supporting Modules (cont.)**

Condition A:  $V_{CC} = 5.0V \pm 10\%$ ,  $\emptyset = 0.5$  to 10MHz,  $V_{SS} = 0V$ ,

$T_a = -20$  to  $75^\circ C$  (regular specifications),

$T_a = -40$  to  $85^\circ C$  (wide-range specifications)

Condition B:  $V_{CC} = 3.0V \pm 10\%$ ,  $V_{SS} = 0V$ ,  $\emptyset = 0.5$ MHz to maximum operating frequency,

$T_a = 0$  to  $75^\circ C$

Item	Symbol	Measurement conditions	Condition B		Condition A				Unit			
			5MHz		6MHz		8MHz			10MHz		
			min	max	min	max	min	max		min	max	
TMR	Timer output delay time	tTMOD	Fig. 17-13	–	200	–	100	–	100	–	100	ns
	Timer reset input setup time	tTMRs	Fig. 17-15	100	–	50	–	50	–	50	–	ns
	Timer clock input setup time	tTMCs	Fig. 17-14	100	–	50	–	50	–	50	–	ns
	Timer clock pulse width (single edge)	tTMCWH	Fig. 17-14	1.5	–	1.5	–	1.5	–	1.5	–	t <sub>cy</sub>
	Timer clock pulse width (both edges)	tTMCWL	Fig. 17-14	2.5	–	2.5	–	2.5	–	2.5	–	t <sub>cy</sub>
PWM	Timer output delay time	tPWOD	Fig. 17-16	–	200	–	100	–	100	–	100	ns
SCI	Input clock (Async)	t <sub>scyc</sub>	Fig. 17-17	2	–	2	–	2	–	2	–	t <sub>cy</sub>
	Input clock (Sync)	t <sub>scyc</sub>	Fig. 17-17	4	–	4	–	4	–	4	–	t <sub>cy</sub>
	Transmit data delay time (Sync)	tTXD	Fig. 17-17	–	200	–	100	–	100	–	100	ns
	Receive data setup time (Sync)	tRXS	Fig. 17-17	100	–	100	–	100	–	100	–	ns
	Receive data hold time (Sync)	tRXH	Fig. 17-17	100	–	100	–	100	–	100	–	ns
Ports	Input clock pulse width	tSCKW	Fig. 17-18	0.4	0.6	0.4	0.6	0.4	0.6	0.4	0.6	t <sub>cy</sub>
	Output data delay time	tPWD	Fig. 17-19	–	200	–	100	–	100	–	100	ns
	Input data setup time	tPRS	Fig. 17-19	200	–	50	–	50	–	50	–	ns
	Input data hold time	tPRH	Fig. 17-19	200	–	50	–	50	–	50	–	ns

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**Table 17-6. Timing Conditions of On-Chip Supporting Modules (cont.)**Condition A:  $V_{CC} = 5.0V \pm 10\%$ ,  $\emptyset = 0.5$  to 10MHz,  $V_{SS} = 0V$ , $T_a = -20$  to  $75^\circ C$  (regular specifications), $T_a = -40$  to  $85^\circ C$  (wide-range specifications)Condition B:  $V_{CC} = 3.0V \pm 10\%$ ,  $V_{SS} = 0V$ ,  $\emptyset = 0.5$ MHz to maximum operating frequency, $T_a = 0$  to  $75^\circ C$ 

Item	Symbol	Measurement conditions	Condition B		Condition A				Unit			
			min	max	5MHz		10MHz					
Dual-port	Address access time	tDAA	Fig. 17-20	—	150	—	150	—	150	—	150	ns
RAM read cycle	$\overline{CS}$ access time	tDACS	Fig. 17-20	—	130	—	130	—	130	—	130	ns
	$\overline{OE}$ output delay time	tDOE	Fig. 17-20	—	70	—	70	—	70	—	70	ns
	$\overline{CS}$ output floating time	tDCHZ	Fig. 17-20	—	50	—	50	—	50	—	50	ns
	$\overline{OE}$ output floating time	tDOHZ	Fig. 17-20	—	50	—	50	—	50	—	50	ns
	Output data hold time	tDOH	Fig. 17-20	0	—	0	—	0	—	0	—	ns
Dual-port RAM write cycle	Chip select time	tDCW	Fig. 17-21	100	—	100	—	100	—	100	—	ns
	Address valid time	tDAW	Fig. 17-21	100	—	100	—	100	—	100	—	ns
	Address setup time	tDAS	Fig. 17-21	20	—	20	—	20	—	20	—	ns
	Write pulse width	tDWP	Fig. 17-21	90	—	90	—	90	—	90	—	ns
	Address hold time	tDWR	Fig. 17-21	20	—	20	—	20	—	20	—	ns
	Input data setup time	tDDW	Fig. 17-21	60	—	60	—	60	—	60	—	ns
	Input data hold time	tDDH	Fig. 17-21	15	—	15	—	15	—	15	—	ns

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• Measurement Conditions for AC Characteristics

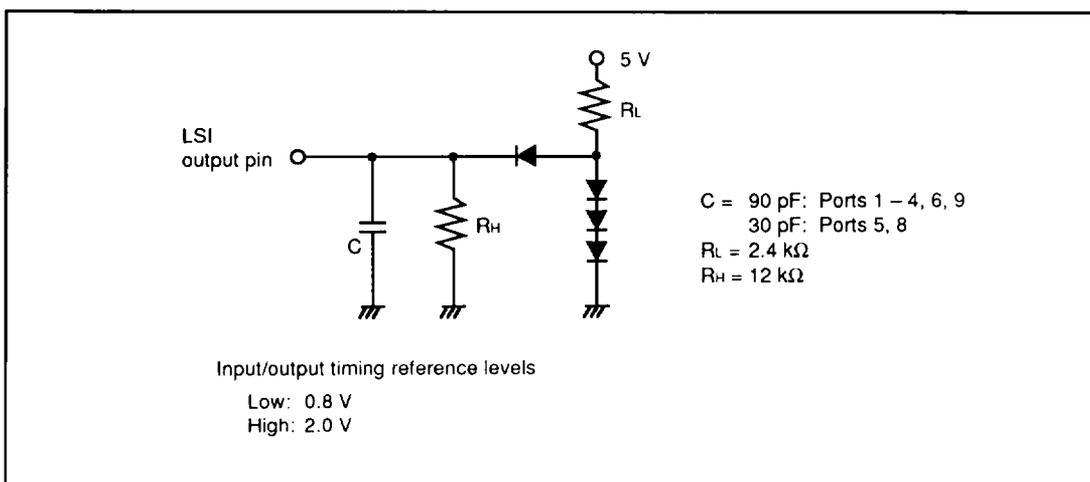


Figure 17-3. Output Load Circuit

17.2.3 A/D Converter Characteristics

Table 17-7 lists the characteristics of the on-chip A/D converter.

Table 17-7. A/D Converter Characteristics

Condition A:  $V_{CC} = AV_{CC} = 5.0V \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0V$ ,

$T_a = -20$  to  $75^\circ C$  (regular specifications),

$T_a = -40$  to  $85^\circ C$  (wide-range specifications)

Condition B:  $V_{CC} = 3.0V \pm 10\%$ ,  $AV_{CC} = 5.0V \pm 10\%$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $\emptyset = 0.5MHz$  to maximum operating frequency,  $T_a = 0$  to  $75^\circ C$

Item	Condition B			Condition A								Unit	
	5MHz			6MHz			8MHz			10MHz			
	min	typ	max	min	typ	max	min	typ	max	min	typ		max
Resolution	8	8	8	8	8	8	8	8	8	8	8	8	Bits
Conversion time (single mode)	–	–	24.4	–	–	20.4	–	–	15.25	–	–	12.2	μs
Analog input capacitance	–	–	20	–	–	20	–	–	20	–	–	20	pF
Allowable signal source impedance	–	–	10	–	–	10	–	–	10	–	–	10	kΩ
Nonlinearity error	–	–	±1	–	–	±1	–	–	±1	–	–	±1	LSB
Offset error	–	–	±1	–	–	±1	–	–	±1	–	–	±1	LSB
Full-scale error	–	–	±1	–	–	±1	–	–	±1	–	–	±1	LSB
Quantizing error	–	–	±0.5	–	–	±0.5	–	–	±0.5	–	–	±0.5	LSB
Absolute accuracy	–	–	±1.5	–	–	±1.5	–	–	±1.5	–	–	±1.5	LSB

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## 17.3 MCU Operational Timing

This section provides the following timing charts:

17.3.1 Bus Timing	Figures 17-4 to 17-6
17.3.2 Control Signal Timing	Figures 17-7 to 17-10
17.3.3 16-Bit Free-Running Timer Timing	Figures 17-11 to 17-12
17.3.4 8-Bit Timer Timing	Figures 17-13 to 17-15
17.3.5 PWM Timer Timing	Figure 17-16
17.3.6 SCI Timing	Figures 17-17 to 17-18
17.3.7 I/O Port Timing	Figure 17-19
17.3.8 Dual-port RAM Timing	Figures 17-20 to 17-21

### 17.3.1 Bus Timing

#### (1) Basic Bus Cycle (Without Wait States) in Expanded Modes

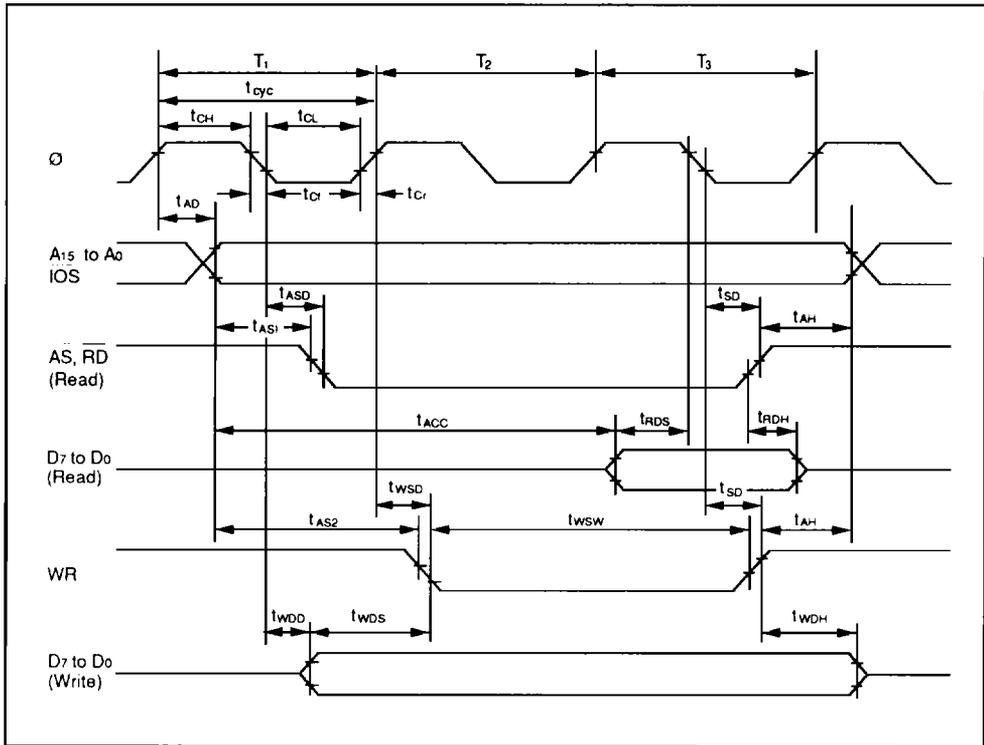


Figure 17-4. Basic Bus Cycle (Without Wait States) in Expanded Modes

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(2) Basic Bus Cycle (With 1 Wait State) in Expanded Modes

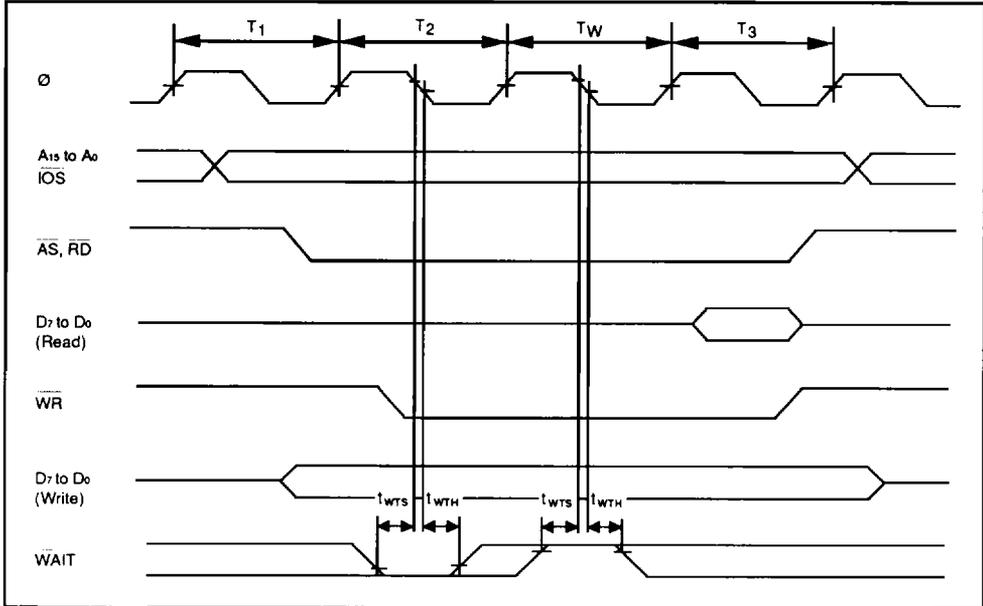


Figure 17-5. Basic Bus Cycle (With 1 Wait State) in Expanded Modes

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### (3) E Clock Bus Cycle

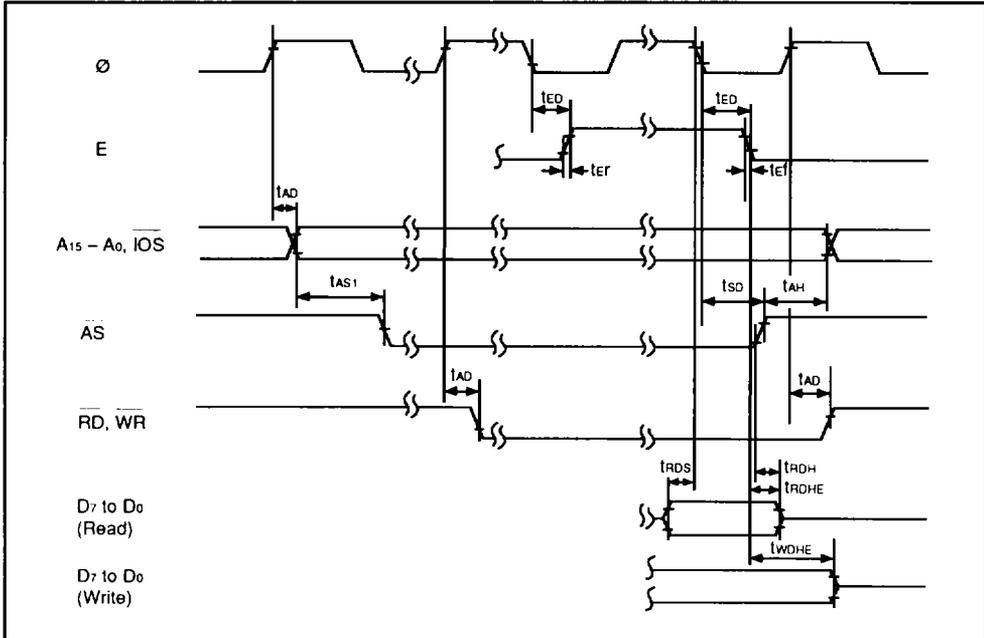


Figure 17-6. E Clock Bus Cycle

## 17.3.2 Control Signal Timing

### (1) Reset Input Timing

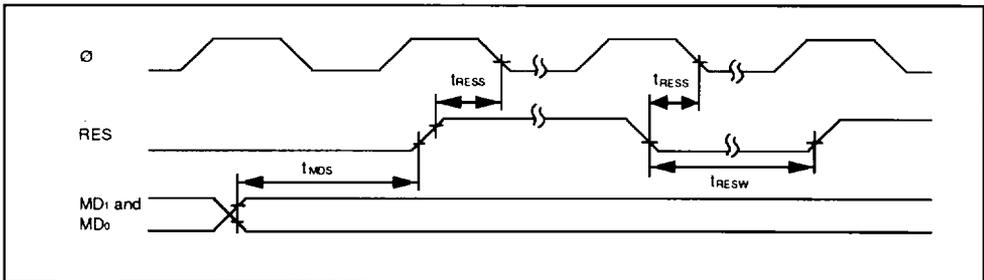


Figure 17-7. Reset Input Timing

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## (2) Interrupt Input Timing

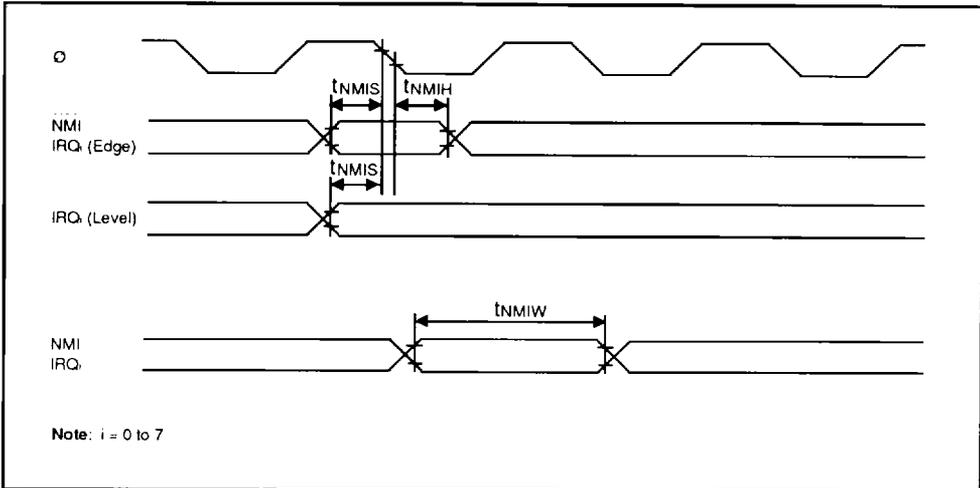


Figure 17-8. Interrupt Input Timing

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### (3) Clock Settling Timing

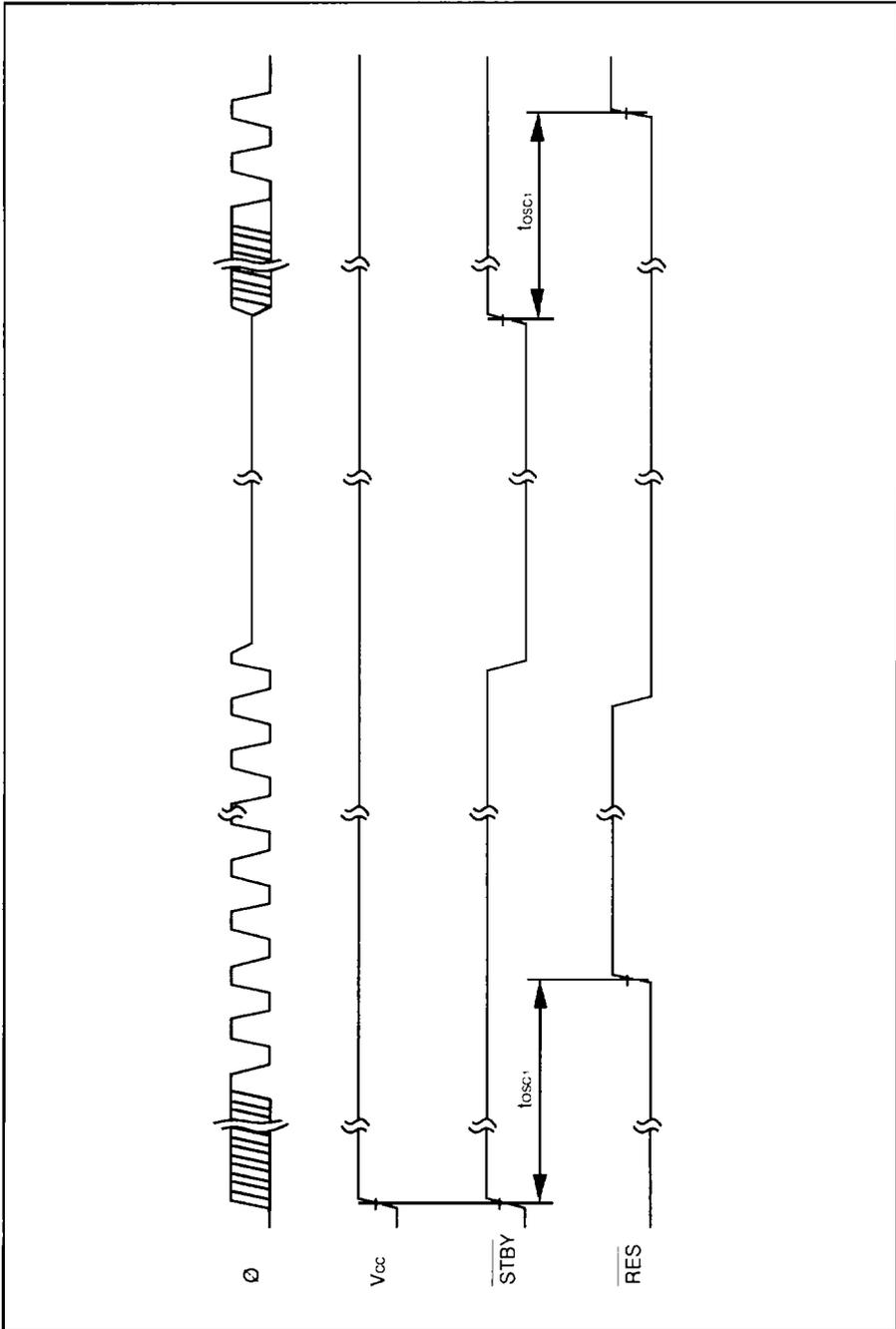
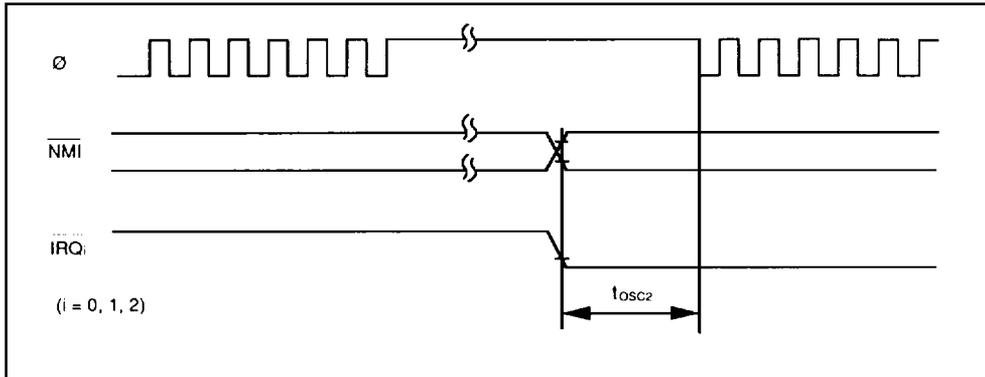


Figure 17-9. Clock Settling Timing

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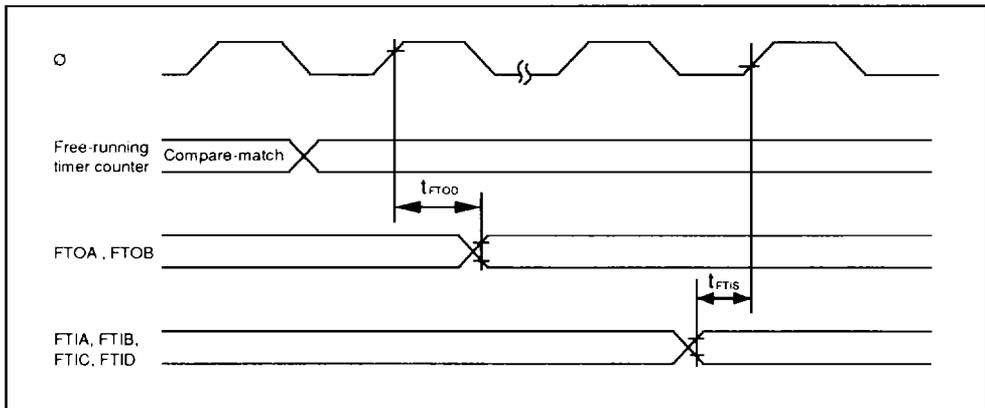
**(4) Clock Settling Timing for Recovery from Software Standby Mode**



**Figure 17-10. Clock Settling Timing for Recovery from Software Standby Mode**

**17.3.3 16-Bit Free-Running Timer Timing**

**(1) Free-Running Timer Input/Output Timing**



**Figure 17-11. Free-Running Timer Input/Output Timing**

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(2) External Clock Input Timing for Free-Running Timer

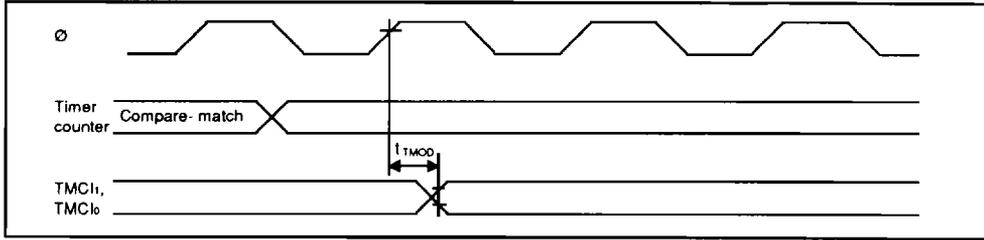


Figure 17-12. External Clock Input Timing for Free-Running Timer

17.3.4 8-Bit Timer Timing

(1) 8-Bit Timer Output Timing

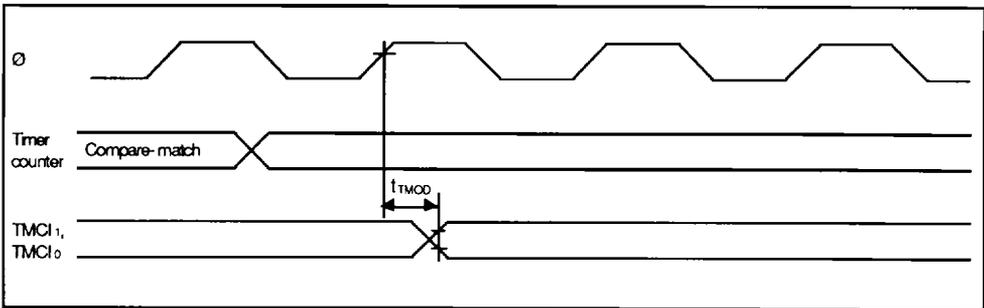


Figure 17-13. 8-Bit Timer Output Timing

(2) 8-Bit Timer Clock Input Timing

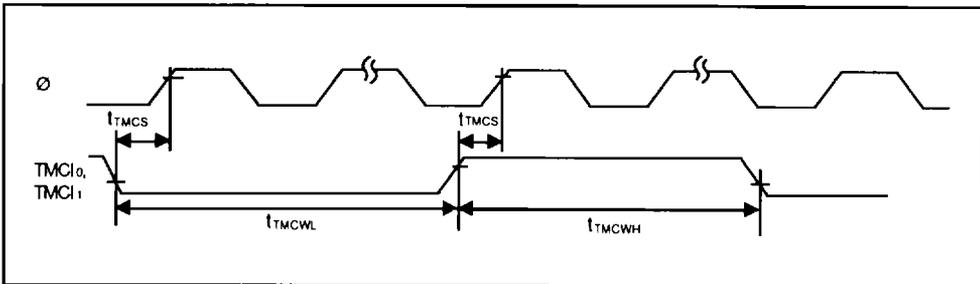


Figure 17-14. 8-Bit Timer Clock Input Timing

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### (3) 8-Bit Timer Reset Input Timing

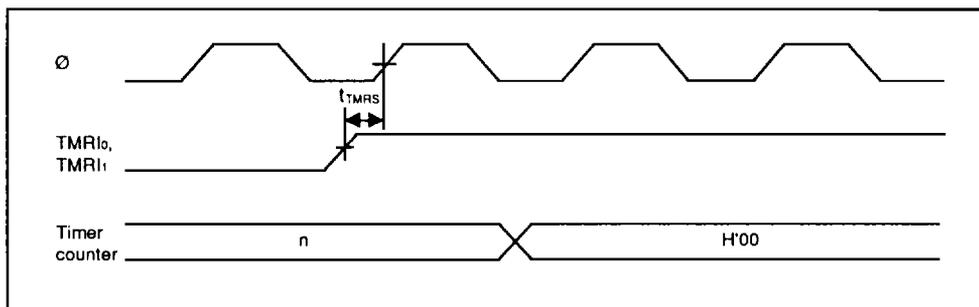


Figure 17-15. 8-Bit Timer Reset Input Timing

### 17.3.5 Pulse Width Modulation Timer Timing

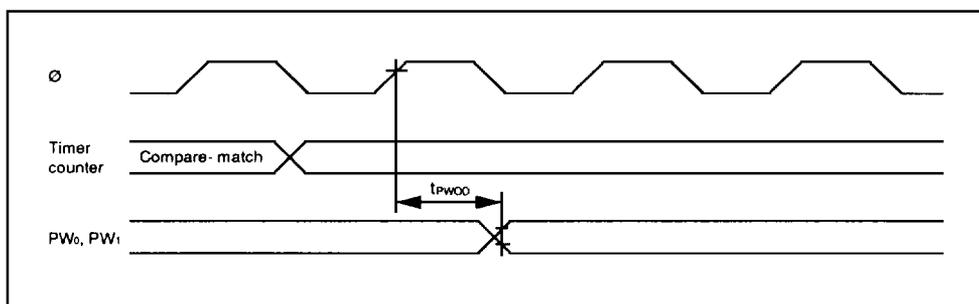


Figure 17-16. PWM Timer Output Timing

### 17.3.6 Serial Communication Interface Timing

#### (1) SCI Input/Output Timing

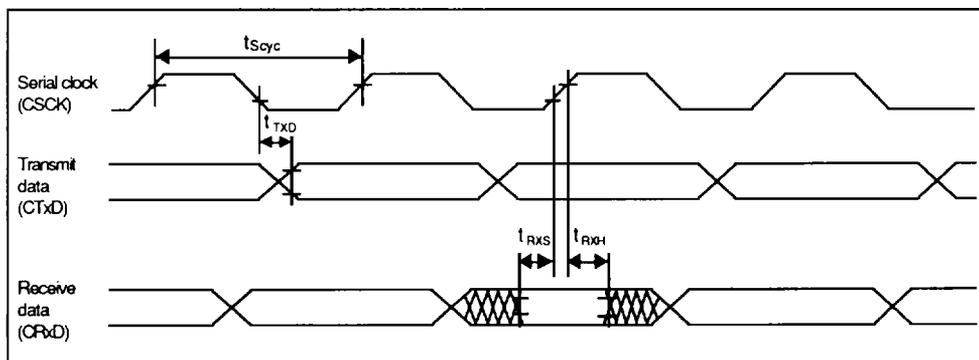


Figure 17-17. SCI Input/Output Timing (Synchronous Mode)

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## (2) SCI Input Clock Timing

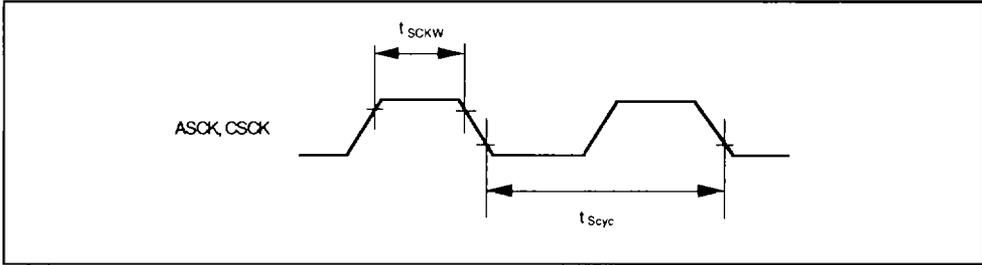


Figure 17-18. SCI Input Clock Timing

### 17.3.7 I/O Port Timing

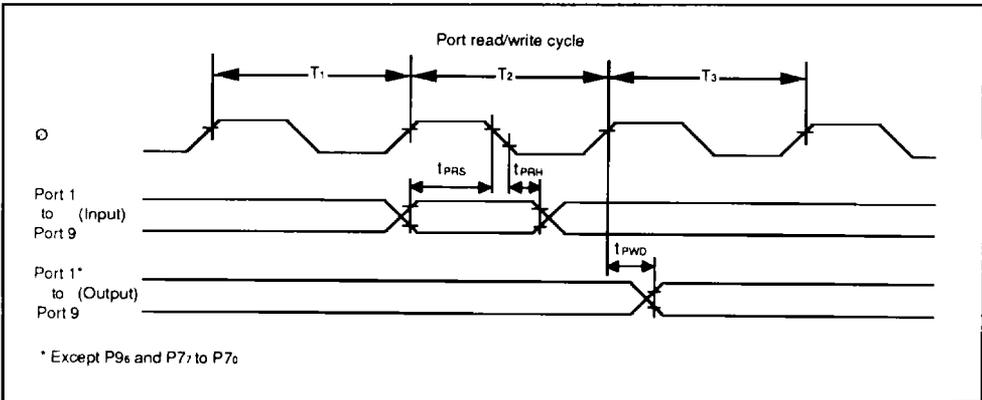


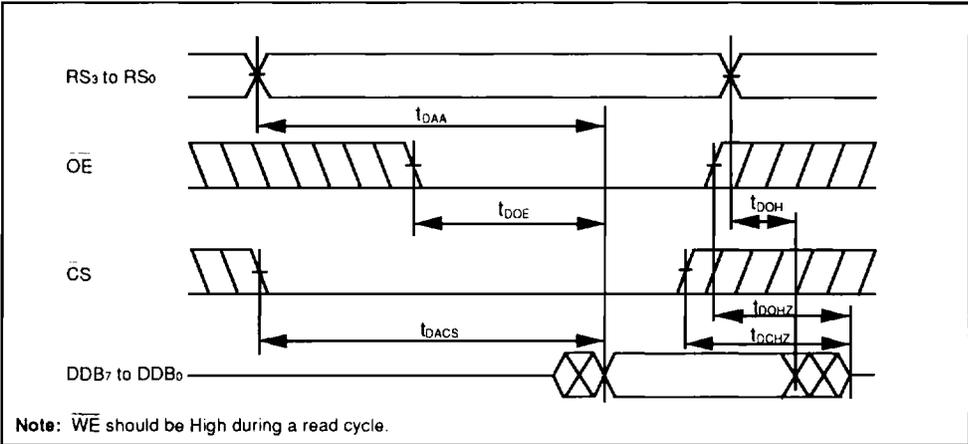
Figure 17-19. I/O Port Input/Output Timing

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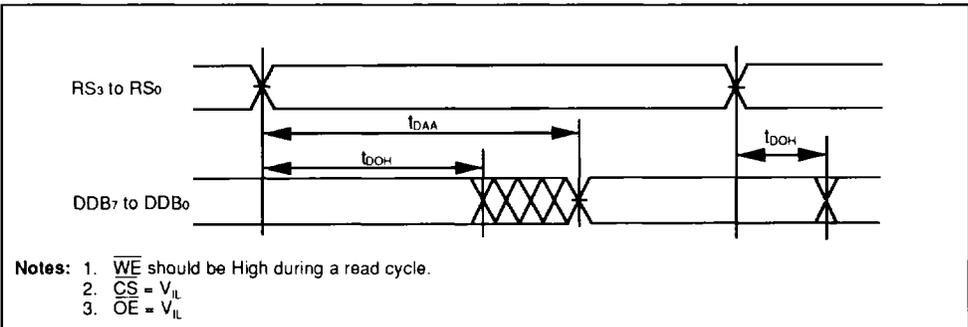
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### 17.3.8 Dual-Port RAM Timing

#### (1) Read Cycle 1



#### (2) Read Cycle 2



#### (3) Read Cycle 3

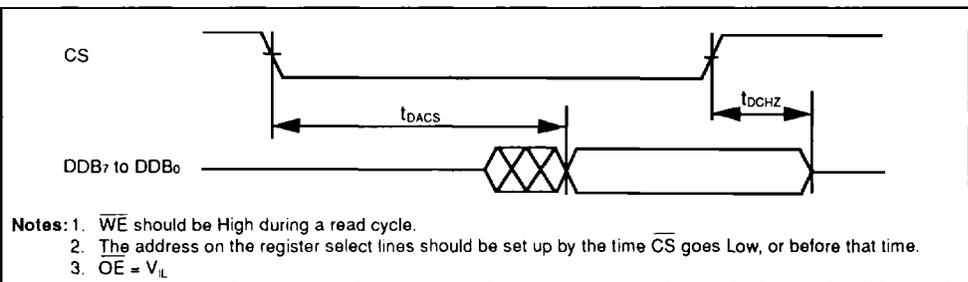


Figure 17-20. Dual-Port RAM Read Timing

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(4) Write Cycle

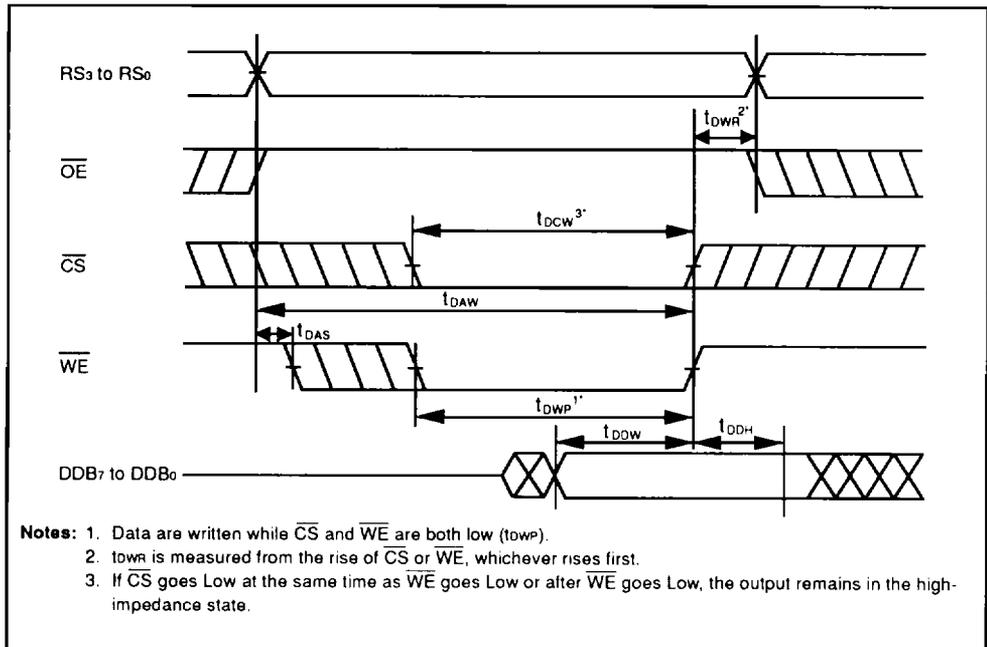


Figure 17-21. Dual-Port RAM Write Timing

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